

Derivation and interpretation of the MilkBot® lactation model in monitoring health of dairy cattle

J.L. Ehrlich, DVM

Dairy Veterinarians Group, Argyle, NY 12809

Introduction

The MilkBot® model is a nonlinear lactation model that has been shown to perform well both in summarizing differences in lactation-curve shape and in projecting future milk production for individual lactations. An understanding of the derivation and assumptions behind the model aids in interpretation of model parameters, which constitute a concise language for summarizing the distribution of milk production within a lactation.

Materials and Methods

Derivation of the MilkBot® model is essentially a thought experiment leading to the equation $MBMilk = scale * EXP(-decay * DIM) * (1 - EXP((offset - DIM) / ramp) / 2)$ where MBMilk is daily milk yield, and the parameter *scale* controls magnitude while *ramp*, *offset*, and *decay* control the shape of the lactation curve.

Results

The effect of individual parameters on curve shape are best shown graphically. The *ramp* parameter

controls the steepness of the post-parturient rise in production. The *decay* parameter controls the decline, most visible in late lactation. The *offset* parameter has minor effect, reflecting the offset between calving and the start of milk production. Fitting a data set to the MilkBot model requires nonlinear fitting methods, for which several strategies are available, depending on the type of input data.

Significance

The MilkBot® model is the first successful attempt to summarize the distribution of milk production within individual or aggregate lactations as a set of parameters related to observable aspects of lactation-curve shape. Fitted parameter values may be used in statistical studies as independent variables or used to project future milk production in incomplete lactations.